IN THE CLAIMS:

Please amend the claims as follows:

1. (Previously presented) A safety controller comprising:

a first and second processing unit communicating on a communication bus, each including a processor and memory, the memory of each of the first and second processing units loadable with a common safety program and input/output variables, wherein the safety program is repeatably executable to read input variables representing inputs from external controlled devices and write output variables representing outputs to external controlled devices at least one processor including a buffer receiving a plurality of input variables asynchronously from I/O circuits connected to sensors;

a coordinator program providing each of the first and second processing units with identical copies of the input variables from the buffer at a predetermined point in the repeated execution of the common safety programs;

a synchronization program executable by the first and second processing units to execute the common safety programs based on the identical copies and to compare execution of the common safety programs and to enter a safety state when this execution differs.

- 2. (Original) The safety controller of claim 1 wherein the coordination program provides identical input variables at only a single point in the repeated execution of the common safety programs.
- 3. (Previously Presented) The safety controller of claim 1 wherein at least one of the processing units further executes a non-safety program and wherein the predetermined point in the repeated execution of the common safety programs is the start of the common safety programs.
- 4. (Original) The safety controller of claim 1 wherein the synchronization program compares execution of the safety program by comparing output variables generated by the first and second processing unit executing the safety program.

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5. (Original) The safety controller of claim 4 wherein the safety program is executed

repeatedly and wherein the comparison of the output variables is performed at the conclusion

of each repeated execution immediately prior to outputting of the output variables to the

external controlled device.

6. (Original) The safety controller of claim 1 wherein the safety program also executes

to generate values of internal variables different from the input and output variables and

wherein the synchronization program compares execution of the safety program by comparing

values of internal variables generated by the first and second processing unit executing the

safety program.

7. (Original) The safety controller of claim 6 wherein the safety program is executed

repeatedly and wherein the comparison is performed at a period greater than the repetition

period.

8. (Original) The safety controller of claim 1 wherein the coordination program stops

the common safety programs execution at the predetermined point in the repeated execution

of the common safety program until the identical input variables have been provided to the

common safety programs.

9. (Cancelled)

10. (Original) The safety controller of claim 1 wherein the communication bus is a

backplane having releasable electrical connectors allowing connection of the first and second

processing unit to and from the backplane.

11. (Original) The safety controller of claim 1 wherein the communications bus is a

serial communications network having releasable electrical connectors allowing connection

of the first and second processing unit to and from the serial communication bus.

12. (Cancelled)

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- 13. (Original) The safety controller of claim 1 wherein the synchronization program combines the output variables when the execution of the common safety program does not differ to produce a single set of output variables transmittable to the controlled device.
- 14. (Original) The safety controller of claim 1 wherein the combination creates a message having one output variable concatenated to the value of the output variable complemented.

15-16. (Cancelled)

- 17. (Previously Presented) A method of operating a safety controller having a first and second processing unit, each including a processor and memory, the memory of each of the first and second processing units loadable with a common safety program and input/output variables, the safety program being repeatably executable to read input variables representing inputs from external controlled devices and write output variables representing outputs to external controlled devices, the method comprising the steps of:
 - (a) accumulating asynchronous input variables in a buffer;
- (a) providing each of the first and second processing units with identical copies of the accumulated input variables from the buffer at a first time at a predetermined point in the repeated execution of the common safety programs; and
- (b) executing by the first and second processing units the common safety programs and comparing execution of the common safety programs to enter a safety state when this execution differs.
- 18. (Original) The method of claim 17 wherein step (a) provides identical input variables at only a single point in the repeated execution of the common safety programs.
- 19. (Original) The method of claim 17 wherein the predetermined point in the repeated execution of the common safety programs is the start of the common safety programs.

- 20. (Original) The method of claim 17 wherein step (b) compares execution of the safety program by comparing output variables generated by the first and second processing unit executing the safety program.
- 21. (Original) The method of claim 20 wherein the safety program is executed repeatedly and wherein step (b) is performed at the conclusion of each repeated execution immediately prior to outputting of the output variables to the external controlled device.
- 22. (Original) The method of claim 17 wherein the safety program also executes to generate values of internal variables different from the input and output variables and wherein step (b) compares execution of the safety program by comparing values of internal variables generated by the first and second processing unit executing the safety program.
- 23. (Previously Presented) The method of claim 17 wherein the safety program is executed repeatedly and wherein the comparison is performed at a period greater than the repetition period.
- 24. (Original) The method of claim 17 wherein step (a) stops the common safety program's execution at the predetermined point in the repeated execution of the common safety program until the identical input variables have been provided to the common safety programs.
- 25. (Original) The method of claim 17 wherein identical input variables are provided by copying of input variables from the first processing unit to the second processing unit.
- 26. (Original) The method of claim 17 wherein the first processing unit includes a buffer memory receiving input variables asynchronously and wherein step (a) copies the buffer memory identically to memory in each of the processing units.
- 27. (Original) The method of claim 17 wherein step (b) combines the output variables when the execution of the common safety program does not differ to produce a single set of output variables transmittable to the controlled device.

28. (Original) The method of claim 17 wherein the combination creates a message having one output variable concatenated to the value of the output variable complemented.

29-30. (Cancelled)